

Standard specifications

RS050NFE02001

March 05, 2015

KAWASAKI HEAVY INDUSTRIES, LTD.

ROBOT DIVISION

Specification :	90101-2316DEA
(Arm) :	90151-0053DEA
(Controller) :	90152-0005DEA

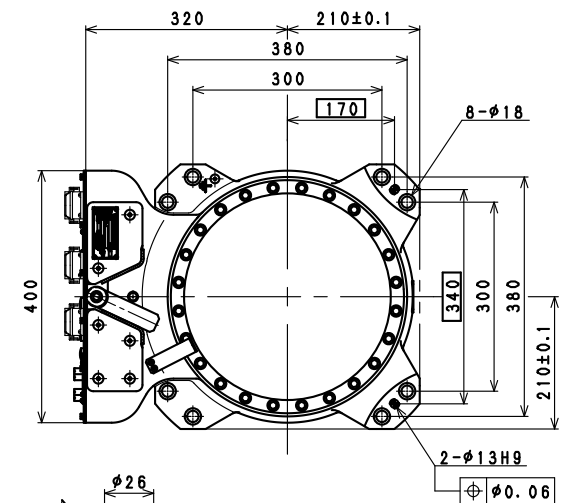
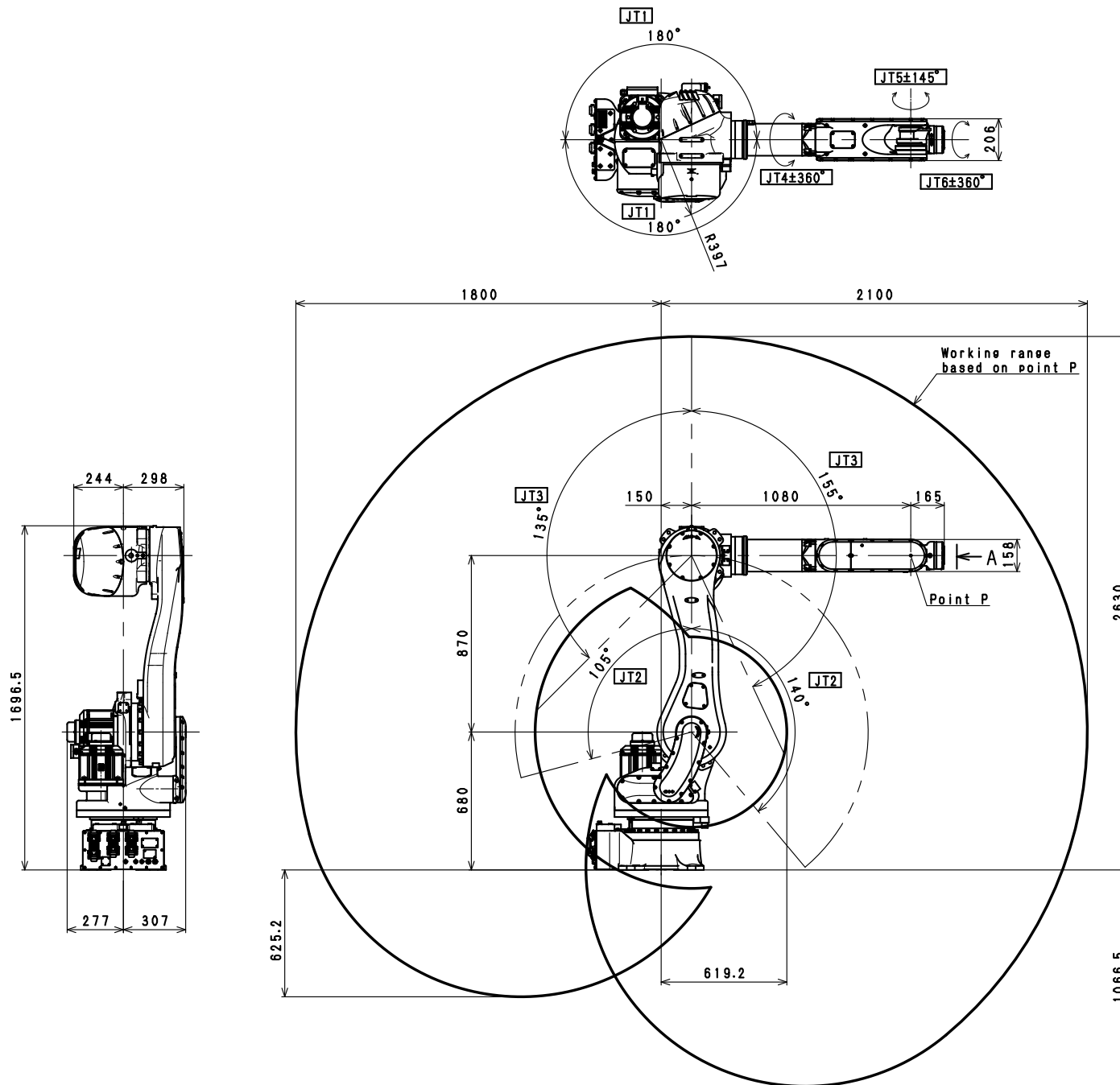
1. Specification of Robot

[1] Robot Arm

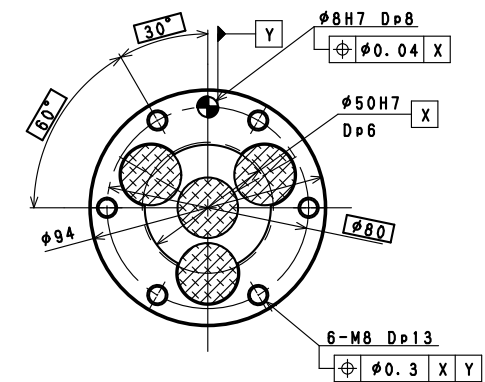
1. Model	RS050N-B		
2. Type	Articulated robot		
3. Degree of freedom	6 axes		
4. Axis specification	Operating axis	Max. operating range	Max. speed
	Arm rotation (JT1)	+180 ° ~ −180 °	180 ° /s
	Arm out-in (JT2)	+140 ° ~ −105 °	180 ° /s
	Arm up-down (JT3)	+135 ° ~ −155 °	185 ° /s
	Wrist swivel (JT4)	+360 ° ~ −360 °	260 ° /s
	Wrist bend (JT5)	+145 ° ~ −145 °	260 ° /s
	Wrist twist (JT6)	+360 ° ~ −360 °	360 ° /s
5. Repeatability	±0.07 mm (at the tool mounting surface)		
6. Max. payload	50 kg		
7. Max. speed	13400 mm/s (at the center of tool mounting surface)		
8. Load capacity of wrist			
		Max. torque	Moment of inertia *
	JT4	210 N•m	28 kg•m ²
	JT5	210 N•m	28 kg•m ²
	JT6	130 N•m	11 kg•m ²
	Note * Each value in this table shows allowable moment of inertia of JT4/JT5/JT6 when max. allowed torque is applied to each axis. If more detailed data is required for your application, please contact Kawasaki.		
9. Driving motor	Brushless AC Servomotor		
10. Working range	See attached drawing		
11. Mass	555 kg (without options)		
12. Color	Munsell 10GY9/1 equivalent		
13. Installation	Floor or Ceiling mounting		
14. Environment cond.	(Temperature) 0 ~ 45 °C, (Humidity) 35 ~ 85 %, no dew, nor frost allowed		
15. Degree of protection	Wrist : IP67 Arm : IP65		
16. Built-in utilities	Pneumatic pipings (φ 10 × 2 lines)		
17. Options	Wall mounting installation		
	Degree of protection of arm : IP67		
	Sensor harness (12 circuits), wired inside robot arm		
	Optional harness (7 pairs), wired inside robot arm		
	Double solenoid/ Single solenoid valves (4 units max.)		
	Air cleaning equipment (filter, regulator, mistseparator)		
	Adjustable mechanical stoppers JT1/JT2/JT3		
	Color (Munsell)		
	Traverse unit (Stroke mm)		
	Arm installation stand (height 600 mm, 300 mm)		
	Arm installation plate (750 mm × 750 mm)		
	18. Others	Consult Kawasaki about maintenance parts and spare parts.	

[2] Controller		
1. Model	E02	
2. Enclosure	Enclosed structure / Indirect cooling system	
3. Dimensions	See attached drawing	
4. Number of controlled axes	Max.9 axes (standard 7 axes, option 2 axes)	
5. Servo control and drive system	Full Digital Servo System	
6. Type of control	Teach mode	Joint, Base, Tool, Fixed Tool (option) operation mode
	Repeat mode	Joint, Linear, Circular (option) interpolation
7. Teaching method	Teaching or AS language programming	
8. Memory capacity	8 MB	
9. External operation signals	External Emergency stop, External Hold, etc.	
10. Number of IO slots	3 slots	
11. Operation panel	Teach/Repeat SW, Emergency Stop SW, Control power lamp	
12. Communication I/F	Ethernet(100BASE-TX) , USB, RS-232C each 2port (1port on panel, 1port inside controller)	
13. Mass	See attached drawing	
14. Power requirement	AC200 V - AC220 V±10%, 50/60 Hz, 3 phases, Max. 7.5 kVA	
15. Ground	Less than 100 Ω (robot dedicated ground) Leakage current: max. 100 mA	
16. Ambient temperature	0 - 45°C	
17. Relative humidity	35 - 85 % (non-condensation)	
18. Color	Munsell: 10GY9/1 equivalent	
19. Teach Pendant	TFT color display (5.7 inch LCD) with touch panel Emergency Stop SW, Teach Lock SW and Enable SW	
20. Safety Circuit	Category: 4, Performance Level: e (EN ISO13849-1) ★	
21. Standard Options		
	General purpose IO board	IN:32 OUT:32 NPN(sink) type or PNP(source) type
	TP sheet language	English or Japanese or Chinese
	I/O connector	D-SUB 37pin(male, female) with cover
	Power/Signal cable	5m, 10m, 15m
	Teach Pendant cable	5m, 10m, 15m
	Transformer unit	AC380V-415V / AC440V-480V by tap selection
22. Other Options		
	Additional IO board	IN:64/96 OUT:64/96 NPN(sink) type or PNP(source) type
	Motor brake release	Manual brake release switch BOX
	PC cable (RS-232C)	1.5 m, 3 m
	External axes control	Additional amplifier and harnesses for external axes
	Extended safety functions	Cubic-S(Motion area monitoring, Joint monitoring, Speed monitoring etc.)
	Teach Pendant option	Connector for TP less
	Fast check mode	Fast check mode Switch
	Others	Field BUS, Software PLC, Analog input/output, Conveyor Synchronization
23. Others	Consult Kawasaki about maintenance parts and spare parts.	

★ Category and Performance level (PL) are determined by the whole system and conditions.
The safety circuit of this controller is available in the system of category: up to 4, PL: up to e.



Installation Dimensions

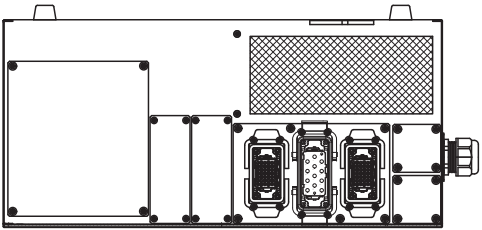


VIEW A

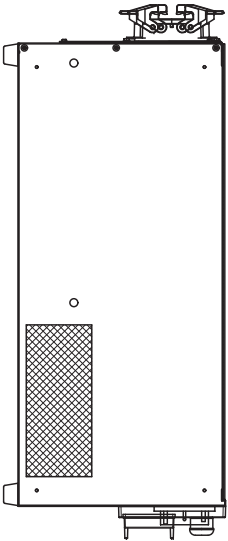
RS050N
WORKING RANGE

E 0 2 C O N T R O L L E R

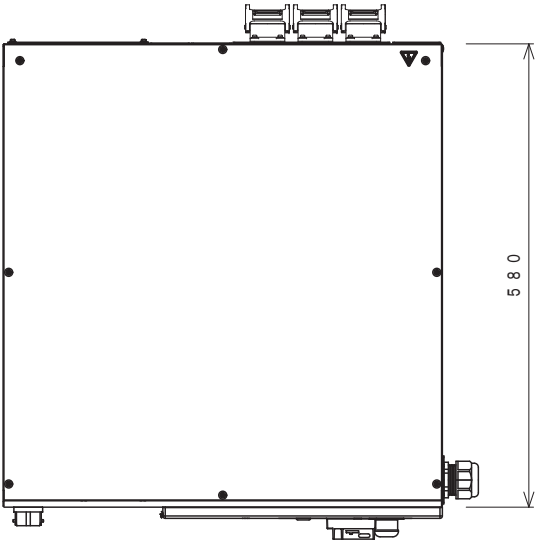
MASS : 4 0 K g



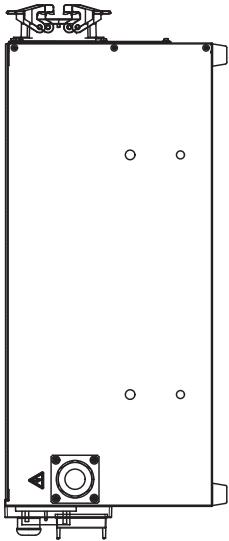
REAR VIEW



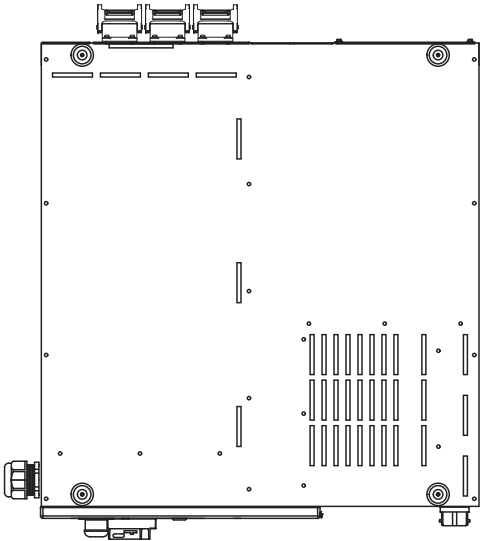
SIDE VIEW



TOP VIEW

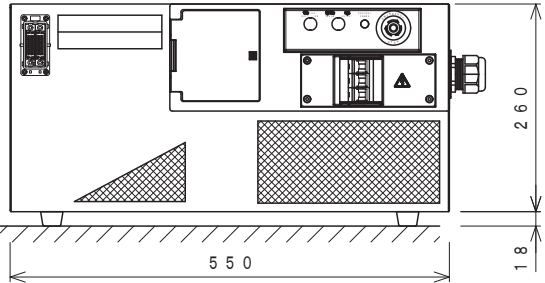
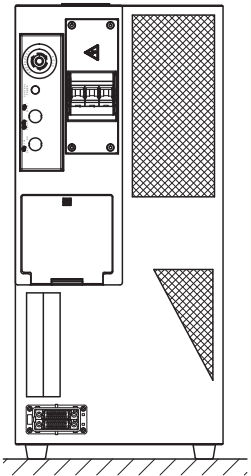


SIDE VIEW



BOTTOM VIEW

Vertical Mount



FRONT VIEW

